Gilbert Yang Ye

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EDUCATION

Ph.D. in Civil Engineering

Ph.D.'s degree program; All but dissertation

- GPA: 4.00/4.00
- Dissertation title: Immersive Human Motor Skill Learning using Haptic Sensation Transfer in Construction
- Supervisor: Dr. Eric Jing Du

M.Sc. in Applied Computational Science and Engineering	Imperial College London
Master's degree program	Sep 2019 - Sep 2020

- Thesis project: A GNSS Satellite Selection Scheme based on Line-of-Sight and Satellite Geometry with a ٠ Machine Learning Approach
- Supervisor: Dr. Anahid Basiri

B.Sc. in Building Engineering and Management

- GPA: 3.62/4.00 (Top 3%)
- Capstone project: A Cost-Benefit Analysis of Building Information Modelling's Application in Building's Life Cycle in Hong Kong
- Supervisor: Dr. Patrick S.W. Fong

Academic Exchange Programs

- University of Maryland: Fall 2017
- University of British Columbia: Summer 2016

ACADEMIC EXPERIENCE

Research Assistant

University of Florida

- Established an innovative pipeline integrating robotic and haptic devices with VR, facilitating the transfer of expert motor skills to novices for enhanced motor skill learning. Successfully applied and validated in Exoskeleton training and welding training.
- Presented the theoretical and practical advancement in using EMG and FNIRS to monitor human cognition.
- Spearheaded the development of embodied AI for construction robotics focusing on two applications: situationalaware drone and force-aware robot arm.
- Took charge of the VR development and coordination for a multi-group NSF convergence accelerator project, contributing to its successful execution and outcomes.

Sep 2020 – Expected May 2024

University of Florida

Hong Kong Polytechnic University Sep 2015 - June 2019

> Sep 2020 - Present Advisor: Dr. Eric Jing Du

Bachelor's degree program

- Mentored and guided two undergraduate student research projects in advanced computing and data collection technology, specifically tailored for the construction industry.
- Played a key role in the composition of four funding proposals and one research center proposal, aiding in securing crucial financial support for cutting-edge research initiatives.

Teaching Assistant

University of Florida

• Conducted tutorials on \underline{BIM} , applied machine learning, and \underline{VR} topics in construction area.

Research Assistant

University of College London

• Utilized Python, GNSSLogger, Laika, Scipy, and OS MasterMap to design and implement an advanced GNSS satellite signal collection, analysis, and filtering scheme based on pseudo-range, LOS, and GDOP. The final product significantly optimized positioning accuracy.

Research Assistant

Hong Kong Polytechnic University

• Spearheaded the data mining and data cleaning efforts for an ECS grant project "Assessing Financial Forecasts in Equity-based Crowdfunding".

Research Assistant

University of Maryland

Sep 2017 – Dec 2017 Advisor: Dr. Qingbin Cui

Aug 2022 - Dec 2022

Mar 2020 - Aug 2020

Aug 2018 - Mar 2019 Advisor: Dr. Shuo Yang

Advisor: Dr. Anahid Basiri

- Conducted comprehensive data collection with World Bank Open Data and executed pilot analysis of the Kuznets Curve Theory, contributing to a deeper understanding of its implications and applications.
- Led a site visit and conducted an extensive literature review to explore the state-of-the-art and state-of-thepractices related to smart city strategy, providing valuable insights for future developments.

PEER-REVIEWED JOURNAL PAPERS

- [1] Wu, J., **Ye, Y.**, & Du, J. (2024). Autonomous Drones in Urban Navigation: Autoencoder Learning Fusion for Aerodynamics. *ASCE Journal of Construction Engineering and Management*. (Impact Factor: 5.8)
- [2] Xia, P., Zhou, T., **Ye, Y.**, & Du, J. (2024). Human Autonomy Teaming for ROV Shared Control. *ASCE Journal of Computing in Civil Engineering*. (Impact Factor: 7.54)
- [3] Wu, J., Ye, Y., & Du, J. (2024). Multi-objective reinforcement learning for autonomous drone navigation in urban areas with wind zones. *ELSEVIER Automation in Construction*, 158, 105253. (Impact Factor: 10.5)
- [4] Ye, Y., Xia, P., Zhou, T., & Du, J. (2023). Spatial Memory of BIM and Virtual Reality: Mental Mapping Study. *ASCE Journal of Construction Engineering and Management*, 149(7), 04023042. (Impact Factor: 5.8)
- [5] Zhou, T., Xia, P., Ye, Y., & Du, J. (2023). Embodied Robot Teleoperation based on High-Fidelity Visual-Haptic Simulator: Pipe Fitting Example. *ASCE Journal of Construction Engineering and Management*. (Impact Factor: 5.8)

- [6] Xia, P., You, H., **Ye, Y.**, & Du, J. (2023). ROV teleoperation via human body motion mapping: Design and experiment. *ELSEVIER Computers in Industry*, 150, 103959. (Impact Factor: 11.245)
- [7] **Ye, Y.**, You, H., & Du, J. (2023). Improved trust in human-robot collaboration with ChatGPT. *IEEE Access*. (Impact Factor: 3.6)
- [8] Zhou, T., Zhu, Q., Ye, Y., & Du, J. (2023). Humanlike Inverse Kinematics for Improved Spatial Awareness in Construction Robot Teleoperation: Design and Experiment. ASCE Journal of Construction Engineering and Management, 149(7), 04023044. (Impact Factor: 5.8)
- [9] **Ye, Y.**, Zhou, T., & Du, J. (2023). Robot-assisted immersive kinematic experience transfer for welding training. *ASCE Journal of Computing in Civil Engineering*, 37(2), 04023002. (Impact Factor: 7.54)
- [10] You, H., Ye, Y., Zhou, T., Zhu, Q., & Du, J. (2023). Robot-Enabled Construction Assembly with Automated Sequence Planning Based on ChatGPT: RoboGPT. *Buildings*, 13(7), 1772. (Impact Factor: 4.3)
- [11] Ye, Y., Shi, Y., Srinivasan, D., & Du, J. (2022). Sensation transfer for immersive exoskeleton motor training: Implications of haptics and viewpoints. *ELSEVIER Automation in Construction*, 141, 104411. (Impact Factor: 10.5)
- Ye, Y., Shi, Y., Xia, P., Kang, J., Tyagi, O., Mehta, R. K., & Du, J. (2022). Cognitive characteristics in firefighter wayfinding Tasks: An Eye-Tracking analysis. *ELSEVIER Advanced Engineering Informatics*, 53, 101668. (Impact Factor: 8.8)

PEER-REVIEWED CONFERENCE PROCEEDINGS

- [13] Ransing, V., Park, J., Ye, Y., Kim, S., Du, J., and Srinivasan, D. How does perceived usefulness of an exoskeleton change with virtual reality training? In *Proceedings of the Human Factors and Ergonomics Society Annual Meeting*. (Accepted)
- [14] Ye, Y., Uthai, T., Xia, P., Zhou, T., and Du, J. User Experience and Workload Evaluation in Robot-Assisted Virtual Reality Welding Training. 2024 ASCE Construction Research Congress (CRC 2024). (Accepted)
- [15] Xu, F., Zhou, T., **Ye, Y.**, and Du, J. Telepresence Robotic Operating System with Mixed Reality. 2024 ASCE Construction Research Congress (CRC 2024). (Accepted)
- [16] Wu, J., **Ye**, **Y.**, and Du, J. Multi-Objective Reinforcement Learning for Autonomous Drone Navigation in Urban Area. *2024 ASCE Construction Research Congress (CRC 2024)*. (Accepted)
- [17] You, H., Ye, Y., Xu, F., and Du, J. Improved Stacked Object Detection with RGB and LiDAR. 2024 ASCE Construction Research Congress (CRC 2024). (Accepted)
- [18] Zhou, T., Xia, P., **Ye, Y.**, and Du, J. Multisensory Augmentation System for Human-Robot Interaction in Construction. 2024 ASCE Construction Research Congress (CRC 2024). (Accepted)
- [19] Ye, Y., Xu, F., and Du, J. Collaborative Virtual Training with Embodied Physics and Haptic Feedback: Construction Material Handling as an Example. *The 2023 ASCE International Conference on Computing in Civil Engineering (i3CE).*
- [20] Zhou, T., Xia, P., **Ye, Y.**, and Du, J. Haptic Augmentation System for Construction Robot Teleoperation. *The 2023 ASCE International Conference on Computing in Civil Engineering (i3CE).*

- [21] Hayes, J., Dwivedi, S., Karthikeyan, R., Abujelala, M., Kang, J., Ye, Y., ... & Mehta, R. K. (2022, September). Identifying early predictors of learning in VR-based drone training. In *Proceedings of the Human Factors and Ergonomics Society Annual Meeting* (Vol. 66, No. 1, pp. 1872-1876). BEST PAPER AWARD
- [22] Ye, Y., Shi, Y., Lee, Y., Burks, G., Srinivasan, D., & Du, J. (2022). Exoskeleton training through haptic sensation transfer in immersive virtual environment. 2022 ASCE Construction Research Congress (CRC 2022) (pp. 560-569)
- [23] Burks, G., Lee, Y., Kim, S., Ye, Y., Beiter, B., Herron, C., ... & Srinivasan, D. (2021, September). A framework for virtual reality-based motor skills training for the use of exoskeletons. In *Proceedings of the Human Factors and Ergonomics Society Annual Meeting* (Vol. 65, No. 1, pp. 277-278). Sage CA: Los Angeles, CA: SAGE Publications.
- [24] **Ye, Y.**, Shi, Y., & Du, J. (2021). Spatial memory of building layout via 2D, 3D, and virtual reality. *The* 2021 ASCE International Conference on Computing in Civil Engineering (i3CE) (pp. 1293-1301).

JOURNAL PAPERS UNDER REVIEW

- [25] **Ye, Y.**, Zhou, T., Zhu, Q., Vann, W., & Du, J. (2024). Brain Functional Connectivity under Teleoperation Latency: a fNIRS Study. *SAGE Human Factors*. (Impact Factor: 2.37) (Under review)
- [26] Zhou, T., Ye, Y., Zhu, Q., Vann, W., & Du, J. (2024). Neural Dynamics of Delayed Feedback in Robot Teleoperation: Insights from fNIRS Analysis. *Frontiers in Human Neuroscience*. (Impact Factor: 2.9) (Under review)
- [27] Du, J., Vann, W., Zhou, T., Ye, Y., & Zhu, Q. (2023). Sensory Manipulation as a Countermeasure to Robot Teleoperation Delays: System and Evidence. *Nature Scientific Reports*. (Impact Factor: 4.6) (Under review)
- [28] Ye, Y., Xia, P., Xu, F., & Du, J. (2023). Enhance Kinesthetic Experience in Welding Motor Training with Virtual Reality and Robotic Arms. *IEEE Transactions on Human-Machine Systems*. (Impact Factor: 3.6) (Under review)
- [29] You, H., Xu, F., Ye, Y., Xia, P., & Du, J. (2023). Adaptive LiDAR Scanning based on RGB Information. ELSEVIER Automation in Construction. (Impact Factor: 10.5) (Under review)
- [30] You, H., Ye, Y., Zhou, T., & Du, J. (2023). : Force-Based Robotic Imitation Learning: A Dual-Loop Approach for Construction Tasks. *ELSEVIER Automation in Construction*. (Impact Factor: 10.5) (Under review)
- [31] Park, J., **Ye**, **Y.**, Du, J., & Srinivasan D. (2023). Virtual reality simulation of exoskeleton-assisted manual material handling. *IEEE Access*. (Impact Factor: 3.6) (Under review)
- [32] You, H., Zhou, T., Qi, Z., Ye, Y., & Du, J. (2023). Embodied AI for Dexterity-Capable Construction Robots: DEXBOT Framework. *IEEE Transactions on Cognitive and Developmental Systems*. (Impact Factor: 4.4) (Under review)
- [33] Wu, J., Ye, Y., & Du, J. (2023). Enhancing Drone Navigation in Urban Environments with Multi-Objective Reinforcement Learning and Convolutional Autoencoder-Generated Wind Simulations. ASCE Journal of Computing in Civil Engineering. (Impact Factor: 7.54) (Under review)

CONFERENCE PRESENTATIONS

- [1] "Collaborative Virtual Training with Embodied Physics and Haptic Feedback: Construction Material Handling as an Example." 2023 ASCE *International Conference on Computing in Civil Engineering* (*i3CE*), Corvallis, Oregon, June 25-28, 2023.
- [2] "Robot-Based Real-Time Point Cloud Digital Twin Modeling in Augmented Reality"*Transforming Construction with Reality Capture Technologies (TCRC) conference 2022*, Fredericton, New Brunswick, Canada, August 23 - 25, 2022.
- [3] "Exoskeleton training through haptic sensation transfer in immersive virtual environment." 2022 ASCE *Construction Research Congress (CRC 2022)*, Arlington, Virginia, March 9–12, 2022.
- [4] "Spatial memory of building layout via 2D, 3D, and virtual reality." 2021 ASCE *International Conference* on *Computing in Civil Engineering (i3CE)*, Orlando, Florida, September 12-14, 2023.

PATENTS

 Du, J., Ye, Y. "Systems and Methods Remote Transferring of Sensation for Physical Motor Training". U.S. Patent Application No.63/371,016. Filed on August 10, 2022.

INVOLVED RESEARCH PROJECTS

Human-Robot Sensory Sharing for Swift Trust in Autonomy	Air Force Office of Scientific Research
(AFOSR)	
Role: Graduate Research Assistant	Dec 2022 - Nov 2025
• Funded amount: \$599,322	

B2: Human-Robot Sensory Transfer for Worker Productivity, Training, and Quality of Life in RemoteUndersea Inspection and Construction TasksNational Science Foundation (NSF)Role: Graduate Research AssistantSept 2021 - Aug 2025

• Funded amount: \$2,090,000

ForceBot: Customizable Robotic Platform for Body-Scale Physical Interaction Simulation in Virtual Reality National Science Foundation (NSF)

Sept 2020- Aug 2024

Nov 2020- Aug 2022

Role: Graduate Research Assistant

• Funded amount: \$312,985

Learning Environments with Augmentation and Robotics for Next-gen Emergency Responders National

Science Foundation (NSF) Role: Graduate Research Assistant

• Funded amount: \$4,998,274

AWARDS

HFES Best Paper AwardHuman Factors and Ergonomics SocietyAwardee2022Awarded for the paper 'Identifying early predictors of learning in VR-based drone training'

Engineering Award - Witters Competition	University of Florida
Awardee	2021
Awarded for excellent engineering design in a community development	plan
The Identification Game	Kaggle Computer Vision Competition
Winner	2020
Awarded for excellent modeling performance	
Deans' Honor List	Hong Kong Polytechnic University
Awardee	2019
Awarded for excellent academic performance	
Outstanding Student Award	Hong Kong Polytechnic University
Awardee	2018
Awarded for one outstanding student per department in overall performa	ince
The Elite of the SeasonBeijing Institution of Residenti	ial Building Design & Research Co. Ltd
Awardee	2018
Awarded for leading the innovation project: Automation of Structural	Horizontal Joint Design and Regulation
Verification	
HKSAR Reaching Out Award	HKSAR
Awardee	2018
Scholarship for meritorious students who actively participated in global	competitions and activities
Global Student Project Fund	Hong Kong Polytechnic University
Funding winner	2017
Funding for supporting student project that has an international view and	d global impact
Global Awareness Award	Hong Kong Polytechnic University
Awardee	2017
Awarded for participating in and organizing international events	
Knowledge and Action Cup Debate Competition	Dongguan Department of Education
Championship	2013

INDUSTRY EXPERIENCE

Ho & Partners Architects Engineers & Development Consultants Ltd	Oct 2018 – Jul 2019
Assistant Surveyor	Hong Kong, China

- Conducted thorough building inspections and generated detailed conditional surveys for Architectural Services Department (ArchSD) Properties under Agreement No. 5VF106, utilizing tools including <u>AutoCAD</u> and <u>Revit</u>.
- Identified and quantified structural risks using <u>OpenCV</u> and <u>Python</u> for informed decision-making and report drafting.
- Demonstrated proficient project coordination skills through seamless communication between government stakeholders, contractors, and consultants, leading to streamlined project execution.
- Prepared comprehensive bidding documents, contributing to successful contract procurement.

Assistant Structure Engineer

- Played a key role in the structural design phase of the Beijing Liulihe Residential District Development Design Project utilizing AutoCAD and PKPM.
- Initiated and led a pilot project focused on automating Structural Horizontal Joint Design and Regulation Compliance Verification utilizing Python and Regex. The project's success improved accuracy and reduced a recurring 3-day workload to a single mouse click.

C&H Properties

IT Assistant

- Initiated and led a pilot innovation project to streamline the annual database maintenance and update workflow.
- Employed powerful tools including BeautifulSoup4 and regex, integrated within the Python programming environment, to automate intricate web-scraping and data processing tasks.
- Successfully achieved exceptional results by transforming a recurring, time-intensive 6-week process into a simple one-click operation.

LEADERSHIP AND SERVICE EXPERIENCES

Care for the Elderly	Feb 2018 - Aug 2018
Volunteer	Hong Kong, China

- Collaborated with the Salvation Army in a service project, regularly visiting elderly individuals living alone in a low-rental public community to understand their living conditions and provide care.
- Led the design and implementation of a comprehensive age-friendly community project, addressing challenges faced by the elderly in Hong Kong and advocating for an inclusive and supportive environment.

Food For Thought: Towards a No-Food-Waste Society

Co-founder and Event Organizer

- Initiated and led a project team to raise awareness and address Hong Kong's food waste problem among students.
- Successfully secured funding from the Hong Kong Polytechnic University's student project fund to support the initiative.
- Coordinated diverse activities, including volunteer events and global promotion sessions, achieving impactful outcomes and leaving a lasting impression on the local community and a global audience.
- Demonstrated strong leadership skills, problem-solving capabilities, and resilience throughout the project's execution.

Meet the underprivileged

Volunteer

- · Visited and connected with vulnerable communities and engaged in meaningful conversations to understand their challenges and aspirations.
- Fostered a safe and open space for the youth to share their stories, hopes, and dreams.

May 2018 – Jul 2018 Beijing, China

Singapore

Jun 2017 – Aug 2017

June 2016 - April 2017

HK & UK

Jan 2017 - Apr 2017 Hong Kong, China

Mandarin Debate Team

Elite

Nov 2015 - May 2017

Hong Kong, China

- Led and represented the Hong Kong Polytechnic University in debating competitions, including the World Mandarin Debating Championship 2018 (Global), RTHK University Debate Competition 2017 (Hong Kong), and Ten-Parties' Debate Competition 2016.
- Demonstrated exceptional communication skills, critical thinking, and teamwork throughout these competitions.

Chinese Mainland Student Association

Chief Secretary

- Proposed and organized the "Sharing Forum," a platform for students to exchange academic and career experiences, featuring diverse speakers to expand horizons and build connections.
- Showcased emcee skills during the association's soiree, engaging the audience and ensuring a memorable and lively event for all attendees.

SKILLS

Programming languages/tools	C#, C++, Python, R, Matlab, SQL, ROS, LATEX, git, Pytorch, Tensorflow, openMP, HPC
Design and simulation	Unity, Unreal Engine, Blender, SketchUp, AutoCAD, Revit, CostX
Industrial knowledge	Mixed Reality; Reinforcement Learning; Embodied AI; Data analysis;
	Building Information Modelling
Interpersonal skills	Communication; Team player; Leadership; Critical thinking